MPiec Machine Controllers



YASKAWA

Global Programming Standard

Many programming languages exist today. Few excel at providing an environment for easily coding of ALL the functionality of modern automated machinery.

That's where Yaskawa's IEC 61131-3 programming environment shines. MotionWorks^{*} IEC encourages the programmer to take advantage of the best of several programming languages within one development package.

- Ladder Logic is perfect for representing digital sensory data.
- Structured Text is a great solution for mathematical algorithms and assignments.
- Function Block Diagrams are best suited for motion control.
- Sequential Function Charts enhance program organization to simplify troubleshooting.
- Object oriented structure promotes programming flexibility and reusable code.

| Hardware and Software Specifications. | | | | |
|--|--|--|--|--|
| MotionWorks' IEC Express | Specifications | | | |
| Motion Interface | PLCopen specification | | | |
| Motion Library | Over 50 function blocks for motion control included | | | |
| Program Languages | IEC 61131-3 languages LD, ST, FB | | | |
| Program Instances | 500 per task | | | |
| Program Tasks | 1 | | | |
| Variables Global | 15000 | | | |
| Variables Local | 15000 per POU | | | |
| Maximum POUs | 2000 Program Organizational Units | | | |
| Configuration | System tuning, monitoring, network data definition | | | |
| Debug Tools | On Screen values, Watch Window, Logic Analyzer, Single Step, Breakpoints | | | |
| MotionWorks [®] IEC Pro Add | itional Specifications | | | |
| Program Languages | IEC 61131-3 languages LD, ST, FB, IL, SFC | | | |
| Program Tasks | 16 per resource | | | |
| Password Protection | Yes | | | |
| MPiec Controller General S | pecifications | | | |
| Ethernet Speed | 100 MB/sec | | | |
| Ethernet Protocols | EtherNet/IP and Modbus/TCP, OPC, and web server support. Custom protocols can be created. | | | |
| Expandable I/O | Digital and Analog, third party devices including temperature controllers | | | |
| MP3200Siec Specifications Axes Maximum Number of Option Cards Configuration Method Dimensions (mm) Communication Motion Interface Mounting Power Input Processor Speed Servo Update Rate | Available in 4, 8, 16, 32, or 62 Axes Virtual Axes: 31 Available with 5 Slot or 8 Slot Module Rack Automatic Configuration of the option cards and MECHATROLINK-III network Power Unit: 64 x 130 x 137; CPU: 35 x 130 x 137; 5-Slot I/O: 126 x 130 x 108; 8-Slot I/O: 184 x 130 x 108 Ethernet, MECHATROLINK-III network Digital MECHATROLINK-III high speed deterministic network DIN rail standard, mounting bracket optional 24 VDC or 100/200 VAC 1 GHz, 64-bit 125 uSec, position loop closed in the amplifier | | | |
| MP2300Siec/MP2310iec Sp | Decifications | | | |
| Axes Maximum | 16 plus additional nodes of remote I/O for a maximum of 21 nodes Virtual Axes: 16 | | | |
| Number of Option Cards | 1 (MP2300Siec) or 3 (MP2310iec) | | | |
| Configuration Method | Automatic Configuration of the option cards and MECHATROLINK-II network | | | |
| Dimensions (mm) | MP2300Siec : 64 x 130 x 108 ; MP2310iec: 120 x 130 x 108 | | | |
| Communication | Ethernet, MECHATROLINK-II network | | | |
| Motion Interface | Digital MECHATROLINK-II network | | | |
| Mounting | DIN rail standard, mounting bracket optional | | | |
| Power Input | 24 VDC | | | |
| Processor Speed | 240 MHz, 32-bit | | | |
| Servo Update Rate | 125 uSec, position loop closed in the amplifier | | | |
| MP2600iec Specifications | (Single-axis Motion Controller Integrated with the Σ -V SERVOPACK) | | | |
| Axes Maximum | 1 servo, 6 virtual, 1 external | | | |
| Configuration Method | Fixed configuration: Servo Axis, Local Digital & Analog I/O and External Encoder | | | |
| Dimensions | See individual Σ -V SERVOPACK dimensions | | | |
| Communication | Two Ethernet connections, on board I/O | | | |
| Motion Interface | Motion control integrated with Σ -V SERVOPACK | | | |
| Mounting | Panel mounting, see individual Σ -V SERVOPACK mounting dimensions | | | |
| Power Input | 120/240/480 V depending on Σ -V SERVOPACK, no other DC input required for controller power | | | |
| Processor Speed | 200 MHz, 32-bit | | | |
| Servo Update Rate | 125 uSec, position loop closed in the amplifier | | | |

Matin/Works® IEC Software

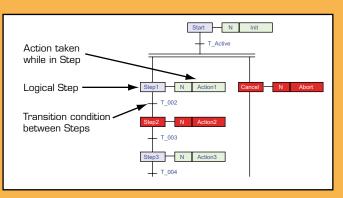
Express and Pro Versions for Simplicity and Flexibility

| Express and Pro | Motion Works IEC | | |
|---|--|---|---|
| | Motio//Works*IEC | | also includes the following: • Password Protection |
| | MUUIUIIWORKS® IEC EXPRESS | PROFESSIONAL | Project Comparison |
| Tasks | 1 | 16 | • POU Grouping |
| 3 (Artes, Mondoer (* 1137193) 4 (Artes, Mondoer (* 1137194) 5 (Artes, Mondoer (* 1137194) 6 (Artes, Mondoer (* 1137194) 7 (Artes, Mondoer (* 1137194) | | CONTRACTOR CONTRACTON CONTRACTON CONTRACTON CONTRACTON CONTRACTON | Duiouitus |
| IEC 61131-3 Languages | Ladder Diagram Function Blocks Structured Text | Ladder Diagram Function Blocks Structured Text | Configurable I/O Task Assignment |
| | | Sequential Function Chart | Auto Save Setting |
| | ur= ServonCo() | 1000 00 00 00 00 00 00 00 00 00 00 00 00 | Debug Powerflow |

Sequential Function Chart.

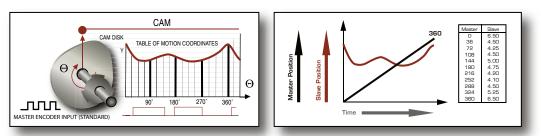
Sequential Function Chart (SFC) is one of the standardized languages available in IEC 61131-3 and is supported in the Professional version of MotionWorks® IEC.

SFC allows the programmer to graphically create program organization in terms of steps, actions, and transitions. Active steps are indicated in red, which simplifies troubleshooting of complex operations.



Camming Function Blocks.

Electronic camming controls the positional relationship of a pair of axes based on a master/slave lookup table



MotionWorks* IEC includes 10 Function Blocks dedicated to camming. These are customized by Yaskawa based on the PLCopen specification, previous controller cam technology, and decades of synchronized motion experience. The function blocks fall into one of four functional topics:

Cam Data Management

Y_CamFileSelect Y CamStructSelect Y ReleaseCam

Cam Engagement Y_CamIn Y CamOut

On-the-Fly Adjustments Y_CamShift Y CamScale Y SlaveOffset

Cam Data Transfer Y ReadCamTable Y WriteCamTable

The Standard in Mechatronics Control.



The MPiec machine controller series facilitates a new realm of possibilities in the world of machine control. By combining many proven technologies in one platform, Yaskawa offers a powerful system with ample flexibility.

Governed by internationally standardized functions, MPiec machine controllers incorporate a potent motion engine at their core. They include a built-in web server and are compatible with the most popular network protocols.

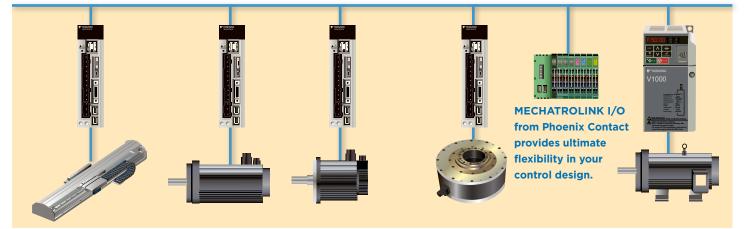
Yaskawa's superior-quality hardware coupled with industry-standard programming tools, maximizes the total automation system value.

Modular Connectivity



MECHATROLINK

High-Speed Deterministic Motion and I/O Network



Linear Servos Peak Force: 85 - 6,000 N Velocity: up to 5m/s Supply Voltage: 240, 480 VAC **Rotary Sigma Servos Peak Torque:** 13.5 – 1,988 in-lb **Velocity:** up to 5,000 rpm **Supply Voltage:** 120, 240, 480 VAC Direct Drive Servos Peak Torque: 53 - 5,310 in-lb Velocity: up to 500 rpm Supply Voltage: 240 VAC VFDs

Output: V1000 (up to 25 hp) A1000 (up to 1000 hp) Velocity: up to 3,600 rpm base Supply Voltage: 240, 480 VAC



Features and Benefits of Mechatronics Control.

Network Communication:

Built-in EtherNet/IP and Modbus/TCP (master and slave) connect to most PLC's and expanded I/O. An OPC server is available to easily connect to PC's, HMI's, or business systems like MES, ERP, or databases.



Standard Programming Languages:

MotionWorks[®] IEC Software complies to the IEC 61131-3 standard, assuring that programs can be developed and executed with predictable behavior.



PLCopen Function Blocks:

Yaskawa developed the motion control interface to comply with PLCopen, yet preserved the motion algorithms developed over decades of accumulated motion control experience.

Reusable Code:

Libraries enable import and reuse of previously developed logic.



Web Server

All controllers have a built in web server which greatly reduces field maintenance time and allows users to load new programs and update controller firmware without the need for special software.

Controller-Centric Commissioning:

The MECHATROLINK motion network provides a conduit to configure the machine from a single location with one software tool, resulting in minimal commissioning time.

Remote I/O:

Numerous third-party remote I/O modules such as Phoenix, Wago, and Opto 22 can be interfaced with the system via MECHATROLINK or Ethernet.

Local I/O:

Choose from eight option cards offered for the expansion slot to accommodate most automation requirements.

IEC on the Drive

The Σ -V SERVOPACK with 1.5 Axis MP2600iec Motion Controller option module offers a compact controller/ servo combination, providing standardized programming on Yaskawa's latest high quality servo system.

Scalability

One software platform for the MPiec machine controllers allows applications to scale up from single to multiaxis control.

Programmable Amplifier Outputs:

The controller can operate local outputs. This reduces panel cost and space requirements when just a couple of outputs are necessary.

MotionWorks \mathbf{EC} and $\mathbf{\Sigma}$ -V Servos

SERVOPACKs and motors:

- 1.6 kHz Bandwidth
- 20-Bit Absolute Encoder
- Vibration Suppression
- Integrated Safety



Yaskawa Continues to Deliver the New Frontier in Servo Performance

| | Highest Performance in the Industry | Frequency Response of 1.6 kHzSettling Time from 0 to 4 ms |
|--------------------------------------|--|--|
| REFERENCE SPEED | Ease of Use | Tuning-less Function for Real-time Adaptive Tuning Advanced Autotuning for Optimal Gain Adjustment Configure and Tune from MotionWorks[*] IEC |
| | Vibration Control | Advanced Vibration Suppression Function |
| | Reduced Size | Amplifiers and Motors up to 30% Smaller than the Competition |
| Settling Time O to 4 ms [Sigma-5] | Integrated Safety | Integrated Safety Tested According to EN954-1 Safety Category 3 and IEC 61508-1 SIL2 |

IEC on the Drive.

IEC 61131-3 on the \varSigma -V SERVOPACK

- One software platform, MotionWorks^{*} IEC, allows applications to scale up from single to multi-axis control within a standard IEC 61131-3 environment.
- Built-in EtherNet/IP and Modbus/TCP (master and slave) connect to most PLC's and expanded I/O.
- PLCopen Function Blocks in MotionWorks IEC simplify programming.
- Diagnostic Web server reduces field maintenance time.
- Optional OPC server allows for HMI or Data Acquisition.
- Σ -V autotuning and vibration suppression algorithms facilitate easy setup.
- Wide product range of Σ -V (3W to 55kW) enables flexible designs.





System Components

| DESCRIPTIO | NC | PART NUMBER | NOTES | |
|--|-------------------------------------|-------------------------------------|---|--|
| MECHATROLIN | MECHATROLINK-III Network Components | | | |
| | CPU Module | PMC-U-MP320 | □□: Maximum number of MECHATROLINK Axes: 04: 4 • 08: 8 • 16: 16 • 32:32 • 62:62 | |
| MP3200iec | Power Supply Module | JEPMC-PSD3012-E | Input Power: D: 24 VDC • A: 100/200 VAC | |
| | Option Module Rack | JEPMC-BUB300D-E | For optional I/O modules | |
| MECHATROLINK-III Cables JEPMC-V | | JEPMC-W6012-DD-E | □□: Cable Length: A2: 0.2m • A5: 0.5m • 01: 1.0m • 02: 2.0m • 03: 3.0m • 04: 4.0m • 05: 5.0m | |
| | Network Hub | JEPMC-MT2000-E | 8 slave ports | |
| | Battery | JEPMC-BA3001 | Replacement battery | |
| Accessories Power Supply Side Cover JEPMC-OP3001 Replacement power supply side cover | | Replacement power supply side cover | | |
| | Option Base Side Cover | JEPMC-OP3002 | Replacement option base side cover | |
| | Network Termination Resistor | N/A | Not required for MECHATROLINK-III network | |

| MECHATROLINK-II Network Components | | | | |
|------------------------------------|------------------------------|------------------|---|--|
| MP2300Siec Controller | Controller | PMC-U-MP23S | without I/O module | |
| | | PMC-U-MP23S | with factory installed LIO-01 | Maximum number of MECHATROLINK Axes: 04: 4 • 08: 8 • 16: 16 |
| | | PMC-U-MP23S | with factory installed LIO-02 | LL: Maximum number of MECHAI ROLINK Axes: 04: 4 • 08: 8 • 16: 16 |
| MP2310iec | Controller | PMC-U-MP231 | without I/O module | |
| MECHATROLINK-II Cables | | JEPMC-W6003-□□-E | □□: Cable Length: A5: 0.5m • 01: 1.0m • | 03: 3.0m • 05: 5.0m • 10: 10.0m • 20: 20.0m |
| | Panel Mounting Bracket | JEPMC-OP2300S-E | For screw mounting MP2300Siec/MP2310iec | |
| Accessories | DIN Rail Clips | JEPMC-OP300 | Extra clips for MP2300Siec/M | P2310iec (2 per set) |
| Accessories | Battery | JZSP-BA01 | Replacement battery | |
| | Network Termination Resistor | JEPMC-W6022 | Required for ends of MECHATROLINK-II network (one included with MP2300Siec) | |

| Single-Axis Controller Option with SERVOPACK | | /OPACK | |
|--|----------------------|----------------------|--|
| MP2600iec | Controller/SERVOPACK | SGDVDDDDE1A002000300 | $\Box\Box\Box\Box$: denotes output capacity and voltage of \varSigma -V SERVOPACK |

| Common Cor | nponents | | | | |
|---|----------------------------|--|---|--|--|
| Software | MotionWorks IEC Express | PDE-U-IE ^{III} Sx | □: Software Version: C : 1 • 2 : 2 | x: Number of Licenses: A : 1 • B : 5 • C : 10 | |
| | MotionWorks IEC Pro | PDE-U-IE D Px | □: Software Version: C:1 • 2:2 | x: Number of Licenses: A : 1 • B : 5 • C : 10 • H: Floating License | |
| | MotionWorks IEC OPC Server | PDE-U-OPCPx | x: Licenses: A:1 B:5 | C:10 D:20 | |
| | | JAPMC-AN2300 | Analog Inputs (AI-01) | (8) channels; +/- 10V @ 16-bit resolution @ 20k Ω or 4-20mA @ 15-bit @ 250 Ω | |
| | | JAPMC-AN2310 | Analog Outputs (AO-01) | (4) channels; +/- 10V @16-bit resolution; 5mA max load current | |
| | | JAPMC-D02300 | Output Module (DO-01) | (64) 24VDC sinking outputs; 100mA/output | |
| Option Cards (for MP3200iec, MP2300Siec, MP2310ie | | JAPMC-102300-E | I/O Module (LIO-01) | (16) 24VDC sinking or sourcing inputs; (16) 24VDC sinking outputs; 100mA/output; (1) Encoder Counter; A/B/C channels; differential; latch response time 5µs; max frequency 500kHz | |
| | | JAPMC-IO2301-E | I/O Module (LIO-02) | (16) 24VDC sinking or sourcing inputs; (16) 24VDC sourcing outputs; 100mA/output; (1) Encoder Counter; A/B/C channels; differential; latch response time 5μ s; max frequency 500 kHz | |
| | | JAPMC-IO2303 | I/O Module (LIO-04) | (32) 24VDC sinking or sourcing inputs; (32) 24VDC sinking outputs; 100mA/output | |
| | | JAPMC-IO2304 | I/O Module (LIO-05) | (32) 24VDC sinking or sourcing inputs; (32) 24VDC sourcing outputs; 100mA/output | |
| | JAPMC-IO2305-E | Multi-Function (LIO-06) I/O Option Module | Analog/Digital/Encoder | | |
| | | JAPMC-CM2301-E | Communications Option (28IF-Y1) | (1) Ethernet port 10 MBit; (1) RS232 port | |
| | | CBK-U-MP2A-DD | For LIO-01/02 | | |
| Terminal Block Conversion Kits | | CBK-U-MP2B- | For LIO-04/05/06/ MP2600iec | □□: Cable Length: A5: 0.5m • 01: 1.0 m • 03: 3.0m | |
| | | SBK-U-VBA- | For SGDV Servo Amp- CN1 | | |
| | | JEPMC-W6080-DD | For AI-01 Analog Input Module | | |
| | | JEPMC-W6090-□□ | For AO-01 Analog Output Module | □□: Cable Length: 05: 0.5m • 10: 1.0 m • 30: 3.0m | |
| Flying Lead Cables (for I/O Modules and MP2600iec) | JEPMC-W6060-DD | For LIO-04/05 I/O Module | | | |
| | JEPMC-W2061-DD | For LIO-01/02 I/O Module | | | |
| | | JEPMC-W2064-DD-E | For LIO-06 I/O Module | □□: Cable Length: | |
| | | CFC-U-MP2B- | For MP2600iec Single Axis Controller | A5: 0.5m • 01: 1.0 m • 03: 3.0m | |
| Accessories | Slot Cover | JEPMC-OP2300 | Front cover for empty slots of | n MP3200iec, MP2300Siec, MP2310iec | |







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Document BL.MWIEC.01 01/16/2014 • © 2013-2014